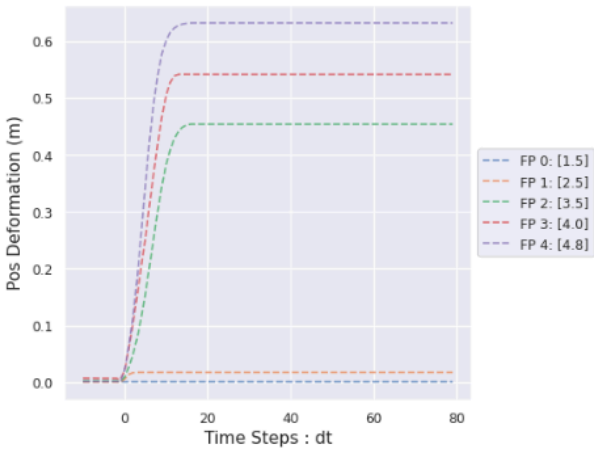
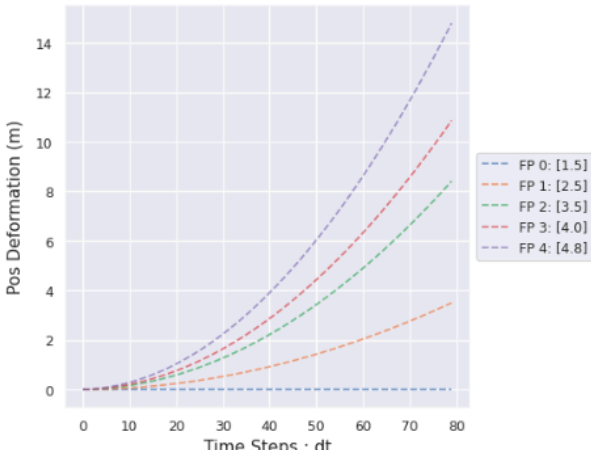
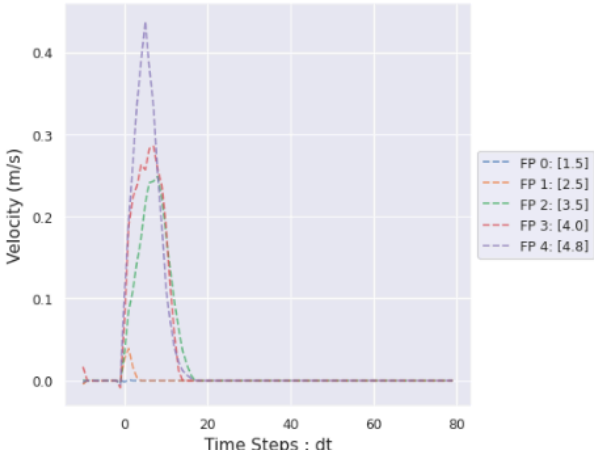
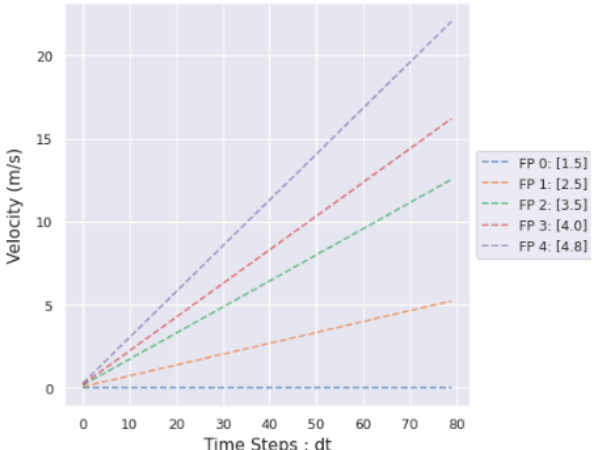


	Actual - With - <del>Jaco2</del> Arm	Expected
Position	<p>GT: Trajectories - Lift Weight - Pos</p>  <p>Pos Deformation (m)</p> <p>Time Steps : dt</p> <p>Legend: FP 0: [1.5], FP 1: [2.5], FP 2: [3.5], FP 3: [4.0], FP 4: [4.8]</p>	<p>GT: Trajectories - Lift Weight - Pos</p>  <p>Pos Deformation (m)</p> <p>Time Steps : dt</p> <p>Legend: FP 0: [1.5], FP 1: [2.5], FP 2: [3.5], FP 3: [4.0], FP 4: [4.8]</p>
Velocity	<p>GT: Trajectories - Lift Weight - Velocity</p>  <p>Velocity (m/s)</p> <p>Time Steps : dt</p> <p>Legend: FP 0: [1.5], FP 1: [2.5], FP 2: [3.5], FP 3: [4.0], FP 4: [4.8]</p>	<p>GT: Trajectories - Lift Weight - Velocity</p>  <p>Velocity (m/s)</p> <p>Time Steps : dt</p> <p>Legend: FP 0: [1.5], FP 1: [2.5], FP 2: [3.5], FP 3: [4.0], FP 4: [4.8]</p>
	*FP = Force Values. E.g. [1.5] means 1.5Newtons applied for 80 time steps	*FP = Force Values. E.g. [1.5] means 1.5Newtons applied for 80 time steps